

Let, $A = \begin{bmatrix} -2 & 1 & 3 \\ 4 & -2 & 5 \end{bmatrix}$

Note that

- 1) The columns of A span \mathbb{R}^2
 - 2) The rows of A are linearly independent
- 1) The columns of A can be "contracted" to form a basis for \mathbb{R}^2 .
- 2) The rows of A can be "expanded" to form a basis for \mathbb{R}^3 .

1) $c_1 = \begin{bmatrix} -2 \\ 4 \end{bmatrix}$ $c_2 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}$ $c_3 = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$

need to ~~at~~ take away a vector, so that the linear remaining ones are linearly independent.

$c_1 = -2c_2 \rightarrow \{c_1, c_2\}$ is linearly dependent:

$c_1 \neq kc_3$ for any $k \in \mathbb{R}$

$c_2 \neq \gamma c_3$ for any $\gamma \in \mathbb{R}$

So either $\{c_1, c_3\}$ or $\{c_2, c_3\}$ is LI

So either of those sets form a basis for \mathbb{R}^2 .

2. $r_1 = \begin{bmatrix} -2 \\ 1 \\ 3 \end{bmatrix}$ $r_2 = \begin{bmatrix} 4 \\ -2 \\ 5 \end{bmatrix}$

Need to find another vector r_3 in \mathbb{R}^3 . Such

that $\{r_1, r_2, r_3\}$ spans \mathbb{R}^3 .

standard basis

②

$$\{i, j, k\}$$

$$\{\varepsilon_1, \varepsilon_2, \varepsilon_3\}$$

make a "good guess" with $\varepsilon_1, \varepsilon_2, \dots$

- in this case, add $\hat{i} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, or $\hat{j} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

So, use either $\{r_1, r_2, \hat{i}\}$ or $\{r_1, r_2, \hat{j}\}$

cannot use $\tilde{k} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ because:

$$2r_1 + r_2 = \begin{bmatrix} -4 \\ 2 \\ 6 \end{bmatrix} + \begin{bmatrix} 4 \\ -2 \\ 5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 11 \end{bmatrix} = 11 \hat{k}$$

3.7

fundamental subspaces of a matrix:

$NS(A)$, $RS(A)$, $CS(A)$

Let A be an $m \times n$ matrix

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & & \vdots \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

Row vectors of A :

$$\begin{aligned} r_1 &= [a_{11} \ a_{12} \ \dots \ a_{1n}] \\ \vdots & \\ r_m &= [a_{m1} \ a_{m2} \ \dots \ a_{mn}] \end{aligned}$$

Column vectors of A :

$$c_1 = \begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix} \dots \dots \dots c_n = \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{bmatrix} \} \Rightarrow \text{in } \mathbb{R}^m$$

Def:

- 1) The subspace of \mathbb{R}^m spanned by row vectors of A is called row space of A denoted $RS(A)$
- 2) The subspace of \mathbb{R}^m spanned by the column vectors of A is called the column space denoted $CS(A)$

Remember:

$NS(A)$ is a subspace of \mathbb{R}^m .

- we have learned how to find a basis and dimension of $NS(A)$
- we want to do the same for $RS(A)$!
- To find basis for $NS(A)$, we used the fact that

$$NS(A) = NS(u) \quad [u \text{ in echelon form of } A]$$

finding a basis for $RS(A)$:

- if A is $m \times n$ and can be reduced to u (row echelon) then $RS(A) = RS(u)$.

find a basis for $RS(A)$

$$A = \begin{bmatrix} 2 & -3 & 4 & 1 & 2 \\ 4 & -6 & 5 & 3 & -4 \\ -10 & 15 & -14 & 3 & 7 \\ 8 & 12 & -10 & 4 & 9 \end{bmatrix} \xrightarrow{\text{row operations}} \begin{bmatrix} 2 & -3 & 4 & 1 & 2 \\ 0 & 0 & -3 & 1 & -8 \\ 0 & 0 & 0 & 10 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} = u$$

Fact:

Let u be a matrix in row echelon form, then the non-zero rows of u form a basis for $RS(u)$.

Use a non-zero row as a basis for $RS(u)$.

\Rightarrow A basis for $RS(A) = RS(u)$ is:

$$\left\{ \begin{bmatrix} 2 \\ -3 \\ 4 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -3 \\ -8 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 10 \\ 1 \end{bmatrix} \right\}$$

Fact:

Dimension of $RS(A)$ is equal to the number of leading variables in u .